

Device Discovery and Beam Tracking

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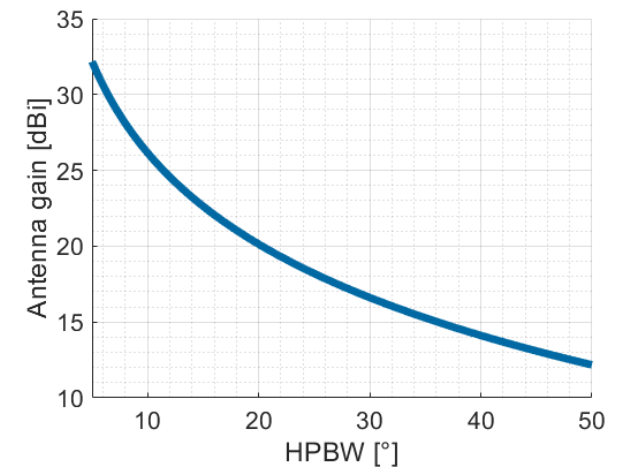
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Motivation

- Low THz frequency range (0.1 – 1 THz) foreseen for next generation communication systems due to high available bandwidth
- In this frequency, range systems suffer from currently low output power devices and high losses
- Antenna gain can be increased in order to overcome losses
- Half-power beamwidth decreases if antenna gain is increased

$$P_{RX} = P_{TX} \cdot G_{TX} \cdot G_{path} \cdot G_{RX}$$

Diagram illustrating the Friis transmission equation with arrows indicating the relationship between variables: P_{TX} (purple arrow pointing down), G_{TX} (green arrow pointing up), G_{path} (purple arrow pointing down), and G_{RX} (green arrow pointing up).

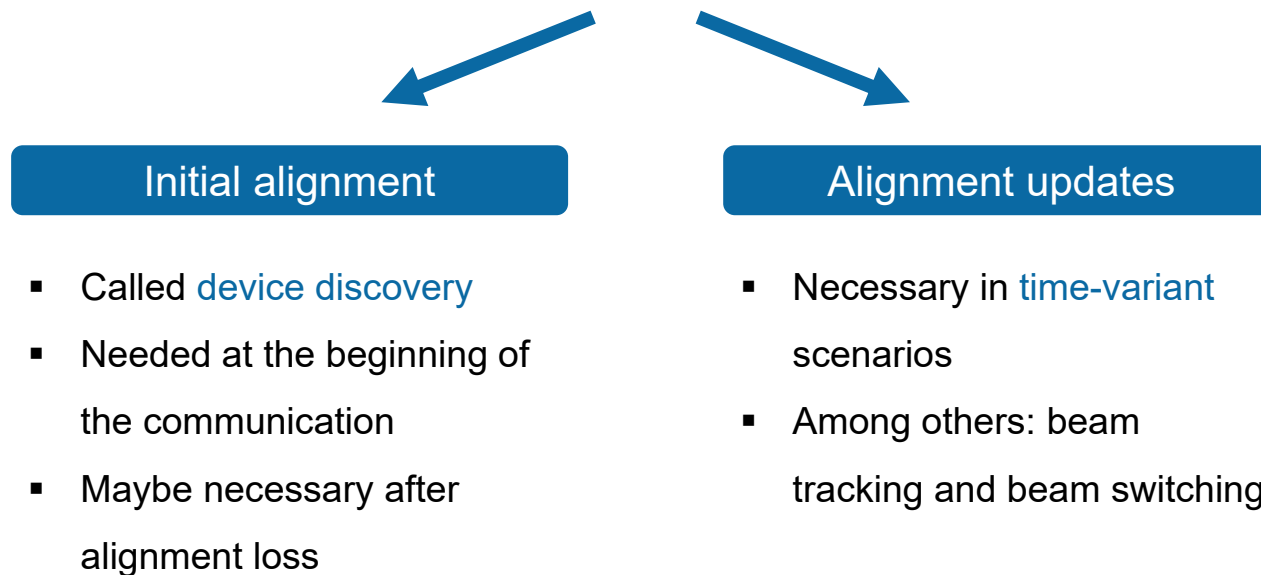


Continuous antenna alignment crucial!



Two phases of antenna alignment

- Antenna alignment can be separated into **two phases**: initial alignment and alignment update

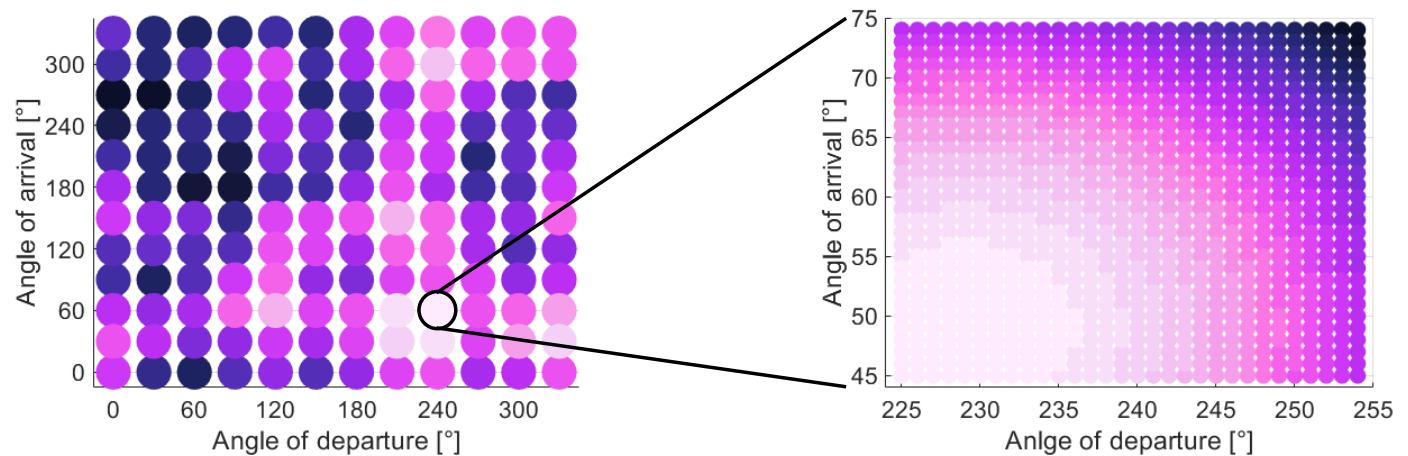
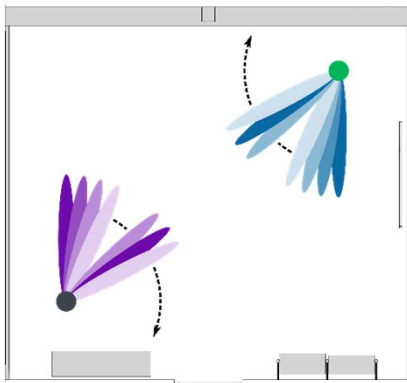


- This work will deal with a novel **device discovery** and **beam tracking** approach

Device discovery

- Approaches utilized in lower frequency ranges often fails due to constraints like, for example, need of omni-directional antennas
- Promising approach: [two-step scanning approach](#)

$$N = \left\lceil \frac{360^\circ}{\Delta\varphi_{\text{init}}} \right\rceil^2 + \left\lceil \frac{\Delta\varphi_{\text{init}}}{\Delta\varphi_{\text{final}}} \right\rceil^2$$



Compressed sensing

- Power angular profile (PAP) given over two-dimensional grid with resolution $\Delta\varphi_{\text{PAP}}$
- Distribution of multipath components (MPCs) in environment can also be given as two-dimensional grid with resolution $\Delta\varphi_{\text{MPC}}$
- The MPCs are mapped to the PAP through the antenna diagram
- In vectorized form: $\mathbf{y} = \mathbf{A}\mathbf{x}$

$\mathbf{y} \in \mathbb{R}^m \quad \hat{=}$ measurement vector; vectorized form of PAP

$\mathbf{A} \in \mathbb{R}^{m \times n} \hat{=}$ measurement matrix including the antenna diagram

$\mathbf{x} \in \mathbb{R}^n \quad \hat{=}$ signal vector; vectorized form of MPC distribution

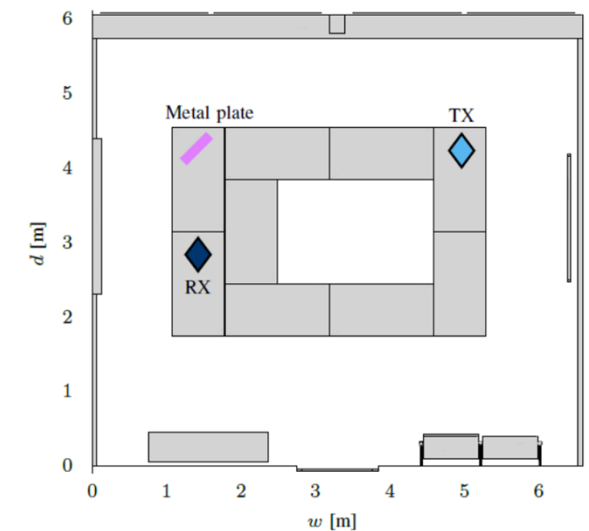
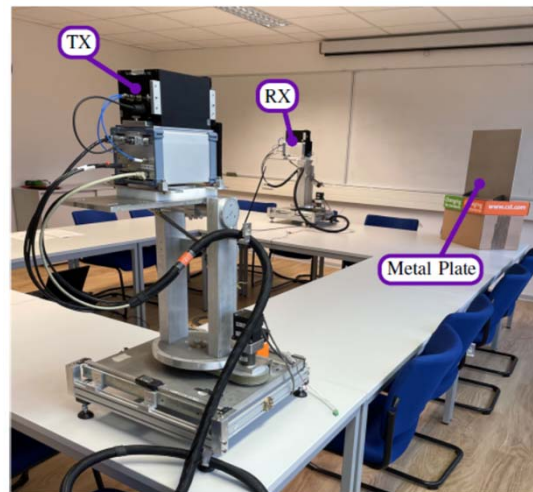
typically: $m \ll n$

➡ Compressed sensing can be used to solve the equation as \mathbf{x} can be assumed to be sparse



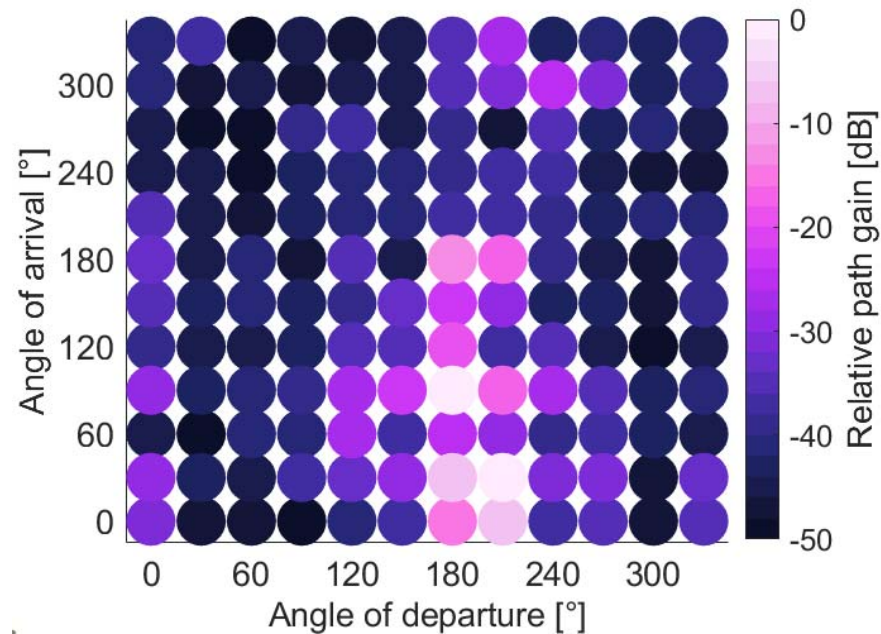
Benefit & measurements

- **MPC distribution**, i.e. signal vector, can be **reconstructed** based on PAP with low angular resolution (**few measurements**)
- PAP can be measured with channel sounder: Each AOD-AOD combination is sum of power of channel impulse response in specific direction
- Available **channel sounder**:
 - correlation-based time-domain channel sounder
 - Center frequency **304.2 GHz** with 8 GHz bandwidth
 - 15 dBi horn antennas with approx. **30° HPBW**

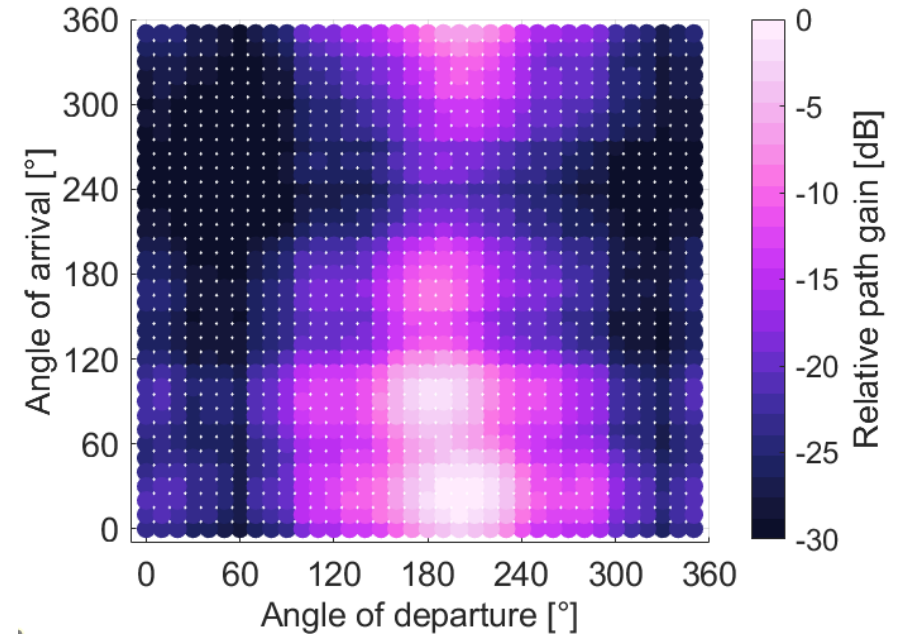


Results

Measured PAP with $\Delta\varphi_{\text{PAP}} = 30^\circ$

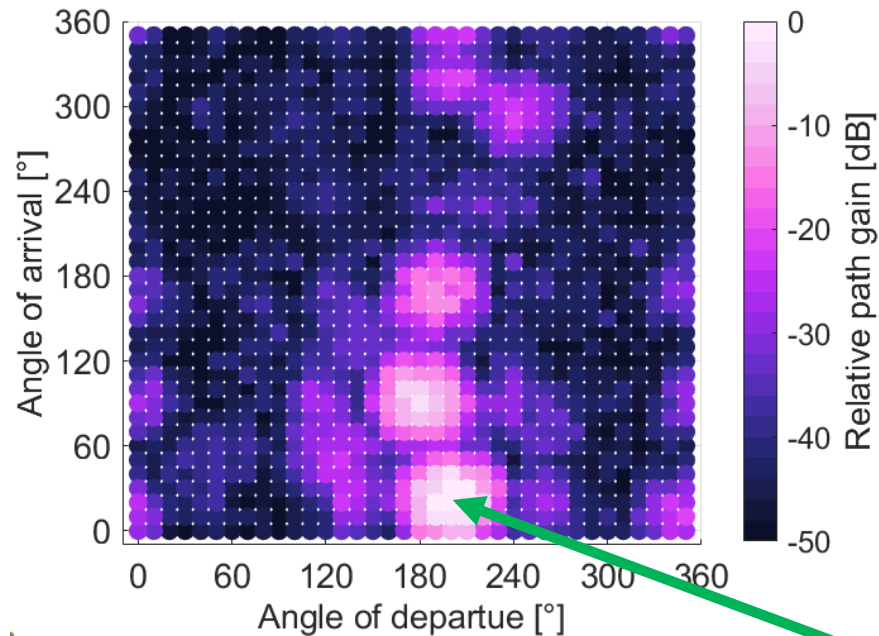


Predicted MPC with $\Delta\varphi_{\text{MPC}} = 10^\circ$

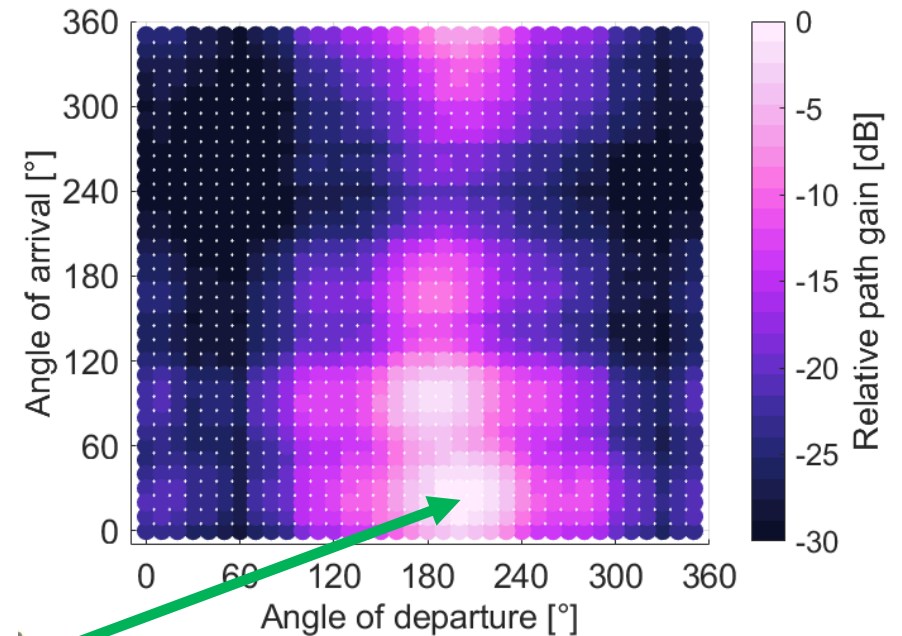


Results

Measured PAP with $\Delta\varphi_{\text{PAP}} = 10^\circ$



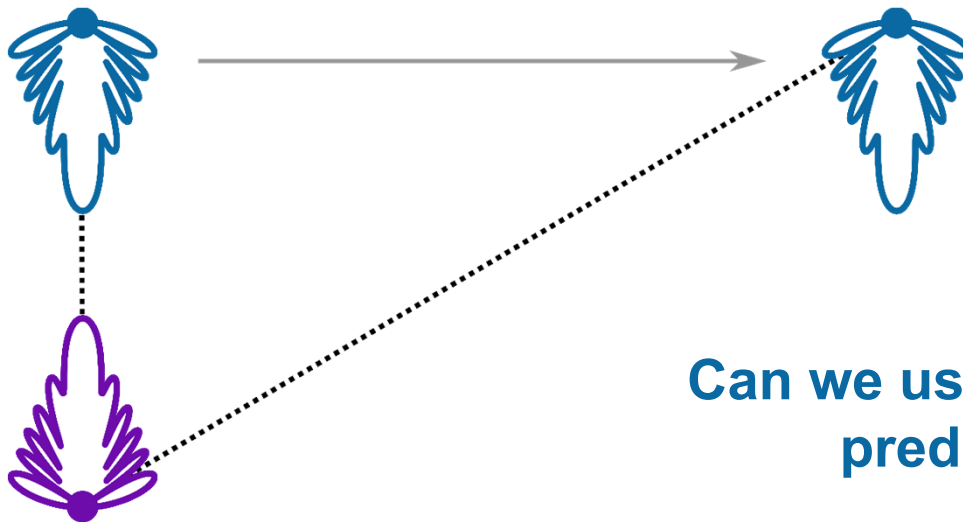
Predicted MPC with $\Delta\varphi_{\text{MPC}} = 10^\circ$



In both cases maximum at AOD = 220° and AOA = 20°

Beam tracking

- After initial alignment further alignment enabled using horn antennas
- Existing methods always require MIMO setups and antenna arrays or are based on movement predictions
- Assumption that relative orientation of antennas does not change during movement



Can we use the change in the path gain for predicting the angular change?

Change of path gain

- Based on Friis equation (assuming LOS condition here):

$$\frac{P_{RX,1}}{P_{RX,0}} = \frac{P_{TX} \cdot G_{TX}(\varphi_{AoD,1}) \cdot G_{FSPL}(d_1) \cdot G_{RX}(\varphi_{AoA,1})}{P_{TX} \cdot G_{TX}(0^\circ) \cdot G_{FSPL}(d_0) \cdot G_{RX}(0^\circ)}$$

- Received power, path loss and antenna gain before movement are known:

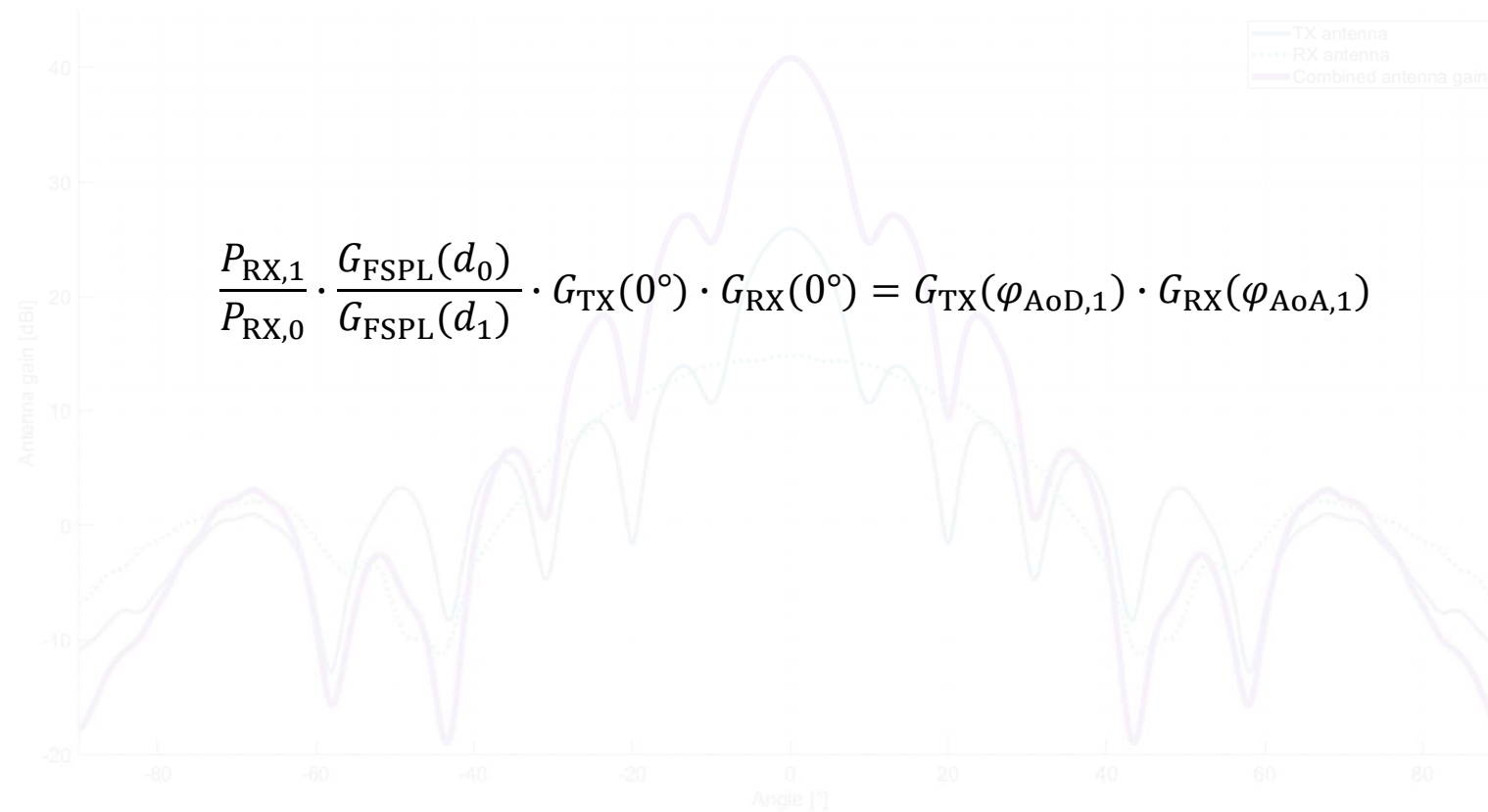
$$\frac{P_{RX,1}}{P_{RX,0}} \cdot \frac{G_{FSPL}(d_0)}{G_{FSPL}(d_1)} \cdot G_{TX}(0^\circ) \cdot G_{RX}(0^\circ) = G_{TX}(\varphi_{AoD,1}) \cdot G_{RX}(\varphi_{AoA,1})$$

- If relative orientation of antennas does not change: antenna gain for each AOD-AOA combination can be calculated

→ *combined antenna gain*



Combined antenna gain



Unique solution

- In order to find unique solution: **More than one antenna** are used with different orientations

- Simulation-based evaluation: 100% accuracy of angle prediction

L. H. W. Löser, T. Doeker and T. Kürner, "Antenna Pattern Tracking Algorithm for Low Terahertz Communications," *2024 18th European Conference on Antennas and Propagation (EuCAP)*, Glasgow, United Kingdom, 2024, pp. 1-5, doi: 10.23919/EuCAP60739.2024.10501488.



- **Measurement-based evaluation:**

- $\pm 1^\circ$ accuracy for angular changes $< 20^\circ$ in **LOS and NLOS** cases
- $\pm 4^\circ$ accuracy for angular changes $< 70^\circ$ (LOS) and $< 45^\circ$ (NLOS)

T. Doeker, L. H. W. Loeser and T. Kürner, "Measurements and Verification of an Antenna Pattern-Based Tracking Algorithm at 300 GHz," in *IEEE Transactions on Terahertz Science and Technology*, vol. 15, no. 3, pp. 359-369, May 2025, doi: 10.1109/TTHZ.2025.3555599.



Conclusion

- Antenna alignment crucial for THz communications
- Important for [initial alignment](#) as well as [continuous alignment](#) in time-varying scenarios
- For initial alignment novel [device discovery](#) approach based on iterative search in combination with [compressed sensing](#)
- Measurement-based evaluation shows correct prediction for measurements taken with 30° increment
- For continuous alignment, here [beam tracking](#), novel approach based on [information of path gain change](#)/ antenna diagram
- Measurement-based evaluation shows prediction $\pm 1^\circ$ accuracy for angular changes $< 20^\circ$ for [LOS and NLOS](#)



Thank you very much for your attention



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